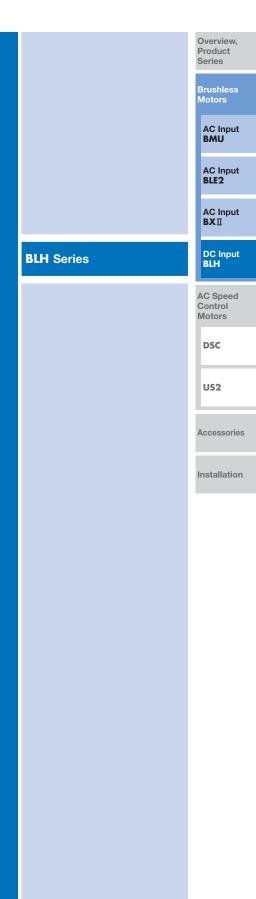
Brushless Motors/AC Speed Control Motors

Brushless Motors
DC Input



Brushless Motors BLH Series

<Additional Information> ● Technical reference → Page H-1 ● Regulations & Standards → Page I-2

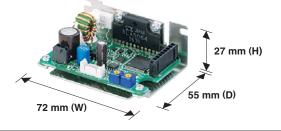
 For detailed information about regulations and standards, please see the Oriental Motor website.



- Combines a slim, high-power brushless motor with a 24 VDC board-type driver.
- Speed control range is 100 to 3000 r/min.
- Output power is 15 W to 100 W.

Features Compact Board-Type Driver

The product with an output of 15 to 50 W adopt a compact, board-type driver smaller than the size of a business card. This will help to reduce the size of your equipment.



The 100 W driver has dimensions of 71 mm (D) \times 131 mm (W) \times 37.5 mm (H)

◇Full Range of Driver Functions

The compact driver is packed with a full range of functions. •Instantaneous stop •Speed control by potentiometer

- •Speed control by DC voltage
- •Acceleration/deceleration time setting •Alarm output

Speed Control Range

100 to 3000 r/min (speed ratio 1:30)

Wide Variety

The series offers a wide range of models from compact packages with a motor output of 15 W, to larger ones producing a high output of 100 W. Choose one that best suits your specific requirements.

IP65 Motor Structure*

The motor is protected against water intrusion, should water come into contact with the motor.

*IP40 for 15 W motor

• The motor must not be washed with water, and is not suitable for use in an environment where it constantly comes into contact with water.

Long Life Gearhead Rating of 10000 Hours*

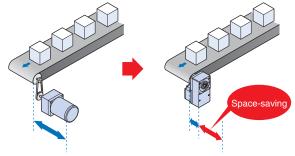
The rated life of the parallel shaft gearhead and hollow shaft flat gearhead is 10000 hours. The parallel shaft gearhead achieves a rated life of twice as long as that of a conventional gearhead. *5000 hours for gearhead equipped with 15 W geared motor.

• The 50 W and 100 W parallel shaft gearhead has a tapped hole at the output shaft end.

Features of Hollow Shaft Flat Gearhead

♦ Space-Saving and Low-Cost

The output shaft can be coupled directly to a driven shaft without using a coupling, which allows you to reduce the size and installation space of your equipment. Since no shaft-coupling parts are needed, the parts cost and labor will also decrease.

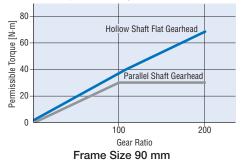


For Three-Phase Motor and Parallel Shaft Gearhead

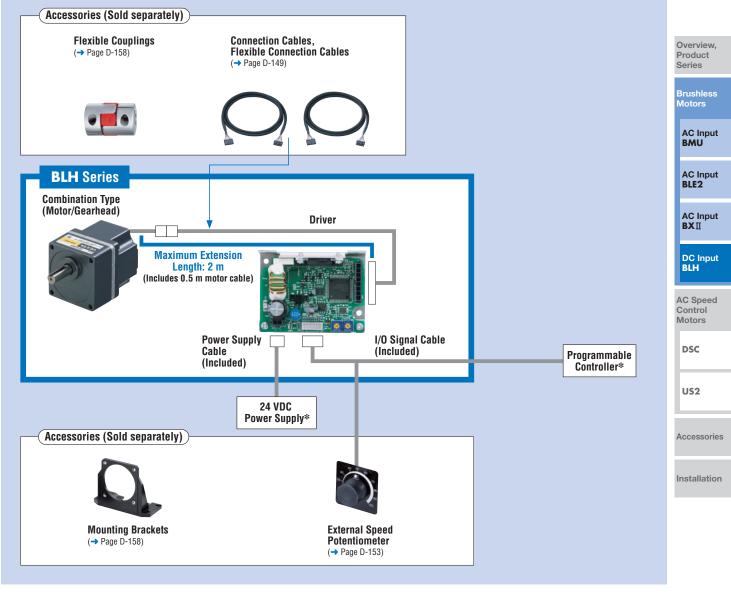
For Brushless Motor and Hollow Shaft Flat Gearhead

$\diamondsuit \mathsf{High}$ Permissible Torque

While the permissible torque of the parallel shaft gearhead saturates at high gear ratios, the hollow shaft flat gearhead enables the motor torque to be fully utilized.



System Configuration



Example of System Configuration

BLH Series			Sold Se	parately	
Combination Type - Parallel Shaft	+	Connection Cable (1.5 m)	External Speed Potentiometer	Mounting Bracket	Flexible Coupling
BLH450KC-30	'	CC02BLH	PAVR-20KZ	SOL4M6	MCL551515
€352.00		€47.00	€11.00	€28.00	€72.00

The system configuration shown above is an example. Other combinations are available.
 *Not supplied

	9	30	V	C	5	ED	1	Series Name	BLH: BLH Series
		30	N		5	ГК	2	Motor Frame Size	0: 42 mm 2: 60 mm 4: 80 mm 5: 90 mm
		\sim					3	Output Power (W)	(Example) 30 : 30 W
(1)	(2)	(3)	(4)	(5)	6	(7)	(4)	Power Supply Voltage	K : 24 VDC
							5	C: Cable Type	
							6	Gear Ratio, Motor Shaft Type	Number: Gear ratio for combination types : 8 types from 5 to 200 Gear ratio for geared types : 7 types from 5 to 100 A: Round Shaft Type
							0		pe - Parallel Shaft Gearhead e - Hollow Shaft Flat Gearhead

Product Line

Combination
TypeThe combination type comes with a motor and gearhead pre-assembled.
The combination of motors and gearheads can be changed, and they are also available separately. In addition, the
gearhead can be removed and the assembly position can be changed in 90° increments.Geared TypeThe geared type has an integrated motor and gearhead. The combination of motor and gearhead cannot be changed.

Geared Types/Combination Types - Parallel Shaft Gearheads

Price includes motor, gearhead and driver.

Туре	Output Power	Product Name	Gear Ratio	List Price
Geared Type	15 W	BLH015K-	5, 10, 15, 20	€276.00
dealed type	13 W		30, 50 , 100	€282.00
			5, 10, 15, 20	€316.00
	30 W	BLH230KC-	30, 50, 100	€323.00
			200	€330.00
Ormhinsting		BLH450KC-	5, 10, 15, 20	€346.00
Combination Type	50 W		30, 50, 100	€352.00
туре			200	€359.00
			5, 10, 15, 20	€420.00
	100 W	BLH5100KC-	30, 50, 100	€429.00
			200	€437.00

The following items are included in each product.
 Motor, Driver, Gearhead, I/O Signal Cable, Power Supply Cable,

Mounting Screws^{*1}, Parallel Key^{*2}, Operating Manual

*1 Combination type only

*2 Products with a key slot on the output shaft only

Round Shaft Types

Price includes motor and driver.

Output Power	Product Name	List Price
15 W	BLH015K-A	€204.00
30 W	BLH230KC-A	€221.00
50 W	BLH450KC-A	€240.00
100 W	BLH5100KC-A	€286.00

• Combination Types - Hollow Shaft Flat Gearheads Price includes motor, gearhead and driver.

Output Power	Product Name	Gear Ratio	List Price
		5, 10, 15, 20	€360.00
30 W	BLH230KC-□FR	30, 50, 100	€369.00
		200	€378.00
		5, 10, 15, 20	€415.00
50 W	BLH450KC-□FR	30, 50, 100	€424.00
		200	€433.00
		5, 10, 15, 20	€498.00
100 W	BLH5100KC-□FR	30, 50, 100	€507.00
		200	€516.00

The following items are included in each product. —

Motor, Driver, Gearhead, I/O Signal Cable, Power Supply Cable, Mounting Screws, Parallel Key, Safety Cover (Screws included), Operating Manual

The following items are included in each product. Motor, Driver, I/O Signal Cable, Power Supply Cable, Operating Manual

Specifications

15 W, 30 W, 50 W, 100 W

Duaduat	Geared Type/Combination Type - Parallel Shaft Gearhead	BLH015K-	BLH230KC-	BLH450KC-	BLH5100KC-		
Product Name	Combination Type - Hollow Shaft Flat Gearhead	-	BLH230KC-□FR	BLH450KC-□FR	BLH5100KC-		
Name	Round Shaft Type	BLH015K-A	BLH230KC-A	BLH450KC-A	BLH5100KC-A		
Rated Out	tput Power (Continuous) W	15	30	50	100		
_	Rated Voltage		24	VDC			
Power	Permissible Voltage Range		±1	0%			
Supply Input	Rated Input Current A	1.0	2.1	3.1	6.0		
mput	Maximum Input Current A	2.4	3.7	5.4	9.8		
Rated Tor	que N·m	0.05	0.12	0.2	0.4		
Instantane	eous Maximum Torque* N·m	0.075	0.15	0.24	0.5		
Rated Spe	eed r/mir	3000	3000 2500				
Speed Co	ntrol Range r/mir	100~3000					
Round Sha Permissib	1×10 ⁻⁷ ka·m ²	0.5	1.8	3.3	5.6		
Rotor Iner	tia J×10 ⁻⁴ kg·m²	0.032	0.087	0.23	0.61		
	Load	$\pm 0.5\%$ max.: Conditions 0~rated torque, rated speed, rated voltage, normal temperature					
Speed Regulation	Voltage	\pm 0.5% max.: Conditions Rated voltage \pm 10%, rated speed, no load, normal temperature					
negulation	Temperature	±0.5% max.: Conditions	Operating ambient temperat	ure 0 \sim +50°C, rated speed,	no load, rated voltage		
-							

*The time during which the instantaneous maximum torque is effective is no more than 5 seconds and at 2000 r/min or below.

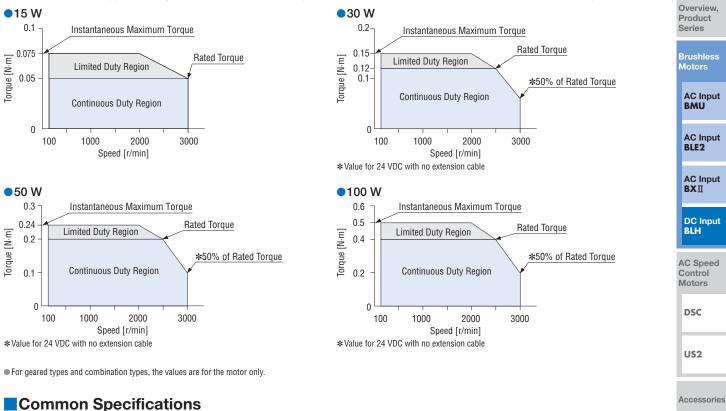
The values in the table are characteristics for the motor only.

ullet A number indicating the gear ratio is entered where the box \Box is located within the product name.

Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region.

Limited Duty Region: This region is used primarily when accelerating. When a load that exceeds the rated torque is applied continuously for approximately five seconds, the overload protective function is activated and the motor coasts to a stop.



Item Specifications Select one of the following methods: Set using the internal speed potentiometer Speed Setting Method · Set using an accessory external speed potentiometer: **PAVR-20KZ** (20 k Ω , 1/4 W) (Sold separately) Set using external DC voltage: 0~5 VDC, 1 mA or more (Input impedance 47 kΩ) 0.5~10 sec BLHO15: at 3000 r/min with no load BLH230, BLH450, BLH5100: at 2500 r/min with no load Acceleration/Deceleration Time (The actual speed may change by load condition.) A common value is set using the acceleration/deceleration time potentiometer. Switching between 2 speeds Multi-Speed Setting Method One speed is set by the internal speed potentiometer (1 pc), while another speed is set by an external speed potentiometer (accessory PAVR-20KZ) or by external DC voltage (0~5 VDC). C-MOS negative logic input Operated by internal power supply Input Signals Common to Start/Stop input, Run/Brake input, Direction of rotation input, Speed control method input and Alarm reset input Open-collector output Operated by external power supply Use condition 26.4 VDC max., 10 mA max. **Output Signals** Common to Alarm output and Speed output When the following are activated, the motor will coast to a stop and the Alarm output will be OFF. The alarm LED on the driver will blink for the corresponding number of times shown in (). · Overload protection (2): Activated when the motor load exceeds rated torque for a minimum of 5 seconds. · Motor sensor error (3): Activated when the sensor wire inside the motor cable is disconnected during motor operation. Protective Functions* • Overvoltage protection (4): Activated when the voltage applied to the driver exceeds 24 VDC by a minimum of approximately 15%, a gravitational operation is performed or a load exceeding the permissible inertia is driven. Undervoltage protection (5): Activated when the voltage applied to the driver falls below 24 VDC by a minimum of approximately 25% Overspeed protection (6): Activated when the motor speed exceeds 3500 r/min. Motor/Driver Distance: 2 m (when an accessory connection cable is used) Maximum Extension Length Time Rating Continuous

*With the **BLH** Series, the motor speed cannot be controlled in a gravitational operation or other application where the motor shaft is turned by the load. When a load exceeding the permissible inertia is driven or a gravitational operation is performed, the overvoltage protective function will be activated and the motor will coast to a stop.

Installation

General Specifications

Item		Motor	Driver				
Insulation Resistance		$100\ M\Omega$ or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity.	100 M Ω or more when 500 VDC megger is applied between the power supply terminal and heat sink after continuous operation under normal ambient temperature and humidity.				
Dielectric Strength		Sufficient to withstand 0.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.	s Sufficient to withstand 0.5 kVAC at 50 Hz applied between the power supply terminal and heat sink for 1 minute after continuous operation under normal ambient temperature and humidity.				
Temperature Rise50°C or less in the windings, and 40°C or less in the case*1, as measured by the thermocouple method after continuous operation under normal ambient temperature and humidity.50°C or less in the heat sink, as measured by the thermo after continuous operation under normal ambient temper humidity.							
	Ambient Temperature	$0 \sim +50^\circ C$ (non-freezing)					
	Ambient Humidity	85% or less (non-condensing)					
	Altitude	Up to 1000 m above sea level					
Operating Environment	Atmosphere	No corrosive gases or dust. Cannot be used in a radioactive	area, magnetic field, vacuum or other special environment				
	Vibration	Not subject to continuous vibration or exc In conformance with JIS C 60068-2-6, "S Frequency range: 10~55 Hz Pulsating a Sweep direction: 3 directions (X, Y, Z) Nu	ine-wave vibration test method" mplitude: 0.15 mm				
	Ambient Temperature	-25~+70°C	(non-freezing)				
Storage Condition*2	Ambient Humidity	85% or less (no	n-condensing)				
	Altitude	Up to 3000 m a	bove sea level				
Thermal Class		UL/CSA standards: 105 (A), EN standards: 120 (E)	-				
Degree of Protection	15 W	IP40	IPOO				
Degree of FIOLECTION	30 W, 50 W ,100 W	IP65 (Excluding the installation surface of the round shaft type and connectors)	ir'UU				

*1 For round shaft types, attach to a heat sink (Material: aluminum) of one of the following sizes to maintain a motor case surface temperature of 90°C max. (Except for 15 W Type)

30 W Type : 115×115 mm, 5 mm thick 50 W Type: 135×135 mm, 5 mm thick 100 W Type: 200×200 mm, 5 mm thick

*2 The storage condition applies to a short period such as a period during transportation.

Note

• Do not measure insulation resistance or perform the dielectric strength test while the motor and driver are connected.

Gearmotor – Torque Table of Geared Type/Combination Type

Geared Types/Combination Types - Parallel Shaft Gearheads.

Gear	red Types/Combination Types - Parallel Shaft Gearheads									
Duril at	G	ear Ratio	5	10	15	20	30	50	100	200
Product Name	Motor Speed	100~2500 r/min	20~500	10~250	6.7~167	5~125	3.3~83	2~50	1~25	0.5~12.5
Name	[r/min]	3000 r/min	600	300	200	150	100	60	30	15
BLH015K-		At 100~3000 r/min	0.23	0.45	0.68	0.86	1.3	2	2	-
BLH23		At 100~2500 r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
DLNZJ		At 3000 r/min	0.27	0.54	0.81	1.1	1.5	2.6	5.2	6
BLH45		At 100~2500 r/min	0.90	1.8	2.7	3.6	5.2	8.6	16	16
DLN43		At 3000 r/min	0.45	0.90	1.4	1.8	2.6	4.3	8.6	16
		At 100~2500 r/min	1.8	3.6	5.4	7.2	10.3	17.2	30	30
BLH5100KC-		At 3000 r/min	0.90	1.8	2.7	3.6	5.2	8.6	17.2	30

A colored background (______) indicates gear shaft rotation in the same direction as the motor shaft. Others rotate in the opposite direction.

Combination Types - Hollow Shaft Flat Gearheads

0000	bination ly	nation types - hollow onalt that dealheads								Unit: N∙m
Draduat	G	ear Ratio	5	10	15	20	30	50	100	200
Product Name	Motor Speed	100~2500 r/min	20~500	10~250	6.7~167	5~125	3.3~83	2~50	1~25	0.5~12.5
Marine	[r/min]	3000 r/min	600	300	200	150	100	60	30	15
ыпор	OKC-□FR	At 100~2500 r/min	0.48	1.0	1.5	2.0	3.1	5.1	10.2	17
DLNZJ	UKC-	At 3000 r/min	0.24	0.51	0.77	1.0	1.5	2.6	5.1	10.2
	OKC-□FR	At 100~2500 r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34
DLN43	UKC-	At 3000 r/min	0.43	0.85	1.3	1.7	2.6	4.3	8.5	17
DILLE 1/	OOKC-□FR	At 100~2500 r/min	1.7	3.4	5.1	6.8	10.2	17	34	68
DLHOI		At 3000 r/min	0.85	1.7	2.6	3.4	5.1	8.5	17	34

• The flat gearhead rotates in the opposite direction to the motor when viewed from the front face of the gearhead. It rotates in the same direction as the motor when viewed from the rear (motor installation surface) of the gearhead. Rotation direction of hollow shaft flat gearhead → Page D-163

Permissible Radial Load and Permissible Axial Load

Geared Types/Combination Types - Parallel Shaft Gearheads

		Permissible	Radial Load	Permissible Axial Load	
Product Name	Gear Ratio	10 mm from Shaft End	20 mm from Shaft End	Permissible Axial Luau	
		N	N	Ν	
BLH015K-	5, 10, 15, 20	50		30	
	30, 50, 100	50	_	30	
	5	100	150		
BLH230KC-	10, 15, 20	150	200	40	
	30, 50, 100, 200	200	300		
	5	200	250		
BLH450KC-	10, 15, 20	300	350	100	
	30, 50, 100, 200	450	550		
BLH5100KC-	5	300	400		
	10, 15, 20	400	500	150	
	30, 50, 100, 200	500	650		

ullet A number indicating the gear ratio is entered where the box \Box is located within the product name.

Brushless Motors/AC Speed Control Motors D-95

Combination Types - Hollow Shaft Flat Gearheads

			Permissible	Permissible Axial Load	
Product Name		Gear Ratio	10 mm from Installation Surface of Gearhead		
			N	N	N
	BLH230KC-	5, 10	450	370	200
	DLH2JVKCFK	15, 20, 30, 50, 100, 200	500	400	200
	BLH450KC-□FR	5, 10	800	660	400
		15, 20, 30, 50, 100, 200	1200	1000	400
		5, 10	900	770	
	BLH5100KC-□FR	15 , 20	1300	1110	500
		30 50 100 200	1500	1280	

● The permissible radial load can also be calculated with a formula. Permissible radial load calculation → Page D-162

Round Shaft Types

	Permissible	Radial Load			
Product Name	10 mm from Shaft End N	20 mm from Shaft End N	Permissible Axial Load		
BLH015K-A	50	_	The neuroiseible suichland		
BLH230KC-A	70	100	The permissible axial load should not be greater than		
BLH450KC-A	120	140	half the motor mass.		
BLH5100KC-A	160	170			

Permissible Inertia: J of Geared Type/Combination Type

Geared Types/Combination Types - Parallel Shaft Gearheads

Product Name	Gear Ratio	5	10	15	20	30	50	100	200	DSC
		3	14	30	50	120	300	600	-	
BLH015K-	When instantaneous stop or instantaneous bi-directional operation is performed	0.4	1.7	3.9	7.0	15.7	43.7	43.7	_	US2
		12	50	110	200	370	920	2500	5000	
BLH230KC-	When instantaneous stop or instantaneous bi-directional operation is performed	1.55	6.2	14.0	24.8	55.8	155	155	155	Accessories
		22	95	220	350	800	2200	6200	12000	
BLH450KC-	When instantaneous stop or instantaneous bi-directional operation is performed	5.5	22	49.5	88	198	550	550	550	
		45	190	420	700	1600	4500	12000	25000	Installation
BLH5100KC-	When instantaneous stop or instantaneous bi-directional operation is performed	25	100	225	400	900	2500	2500	2500	

Combination Types - Hollow Shaft Flat Gearheads

Combination Types - Hollow Shaft Flat Gearheads Unit: ×10 ⁻⁴ kg·m ²									
Product Name	Gear Ratio	5	10	15	20	30	50	100	200
		12	50	110	200	370	920	2500	5000
BLH230KC-□FR	When instantaneous stop or instantaneous bi-directional operation is performed	1.55	6.2	14.0	24.8	55.8	155	155	155
		22	95	220	350	800	2200	6200	12000
BLH450KC-□FR	When instantaneous stop or instantaneous bi-directional operation is performed	5.5	22	49.5	88	198	550	550	550
		45	190	420	700	1600	4500	12000	25000
BLH5100KC-□FR	When instantaneous stop or instantaneous bi-directional operation is performed	25	100	225	400	900	2500	2500	2500

Unit: ×10⁻⁴ kg⋅m²

● A number indicating the gear ratio is entered where the box □ is located within the product name.



Overview, Product Series

Brushless Motors

AC Input BMU

AC Input BLE2

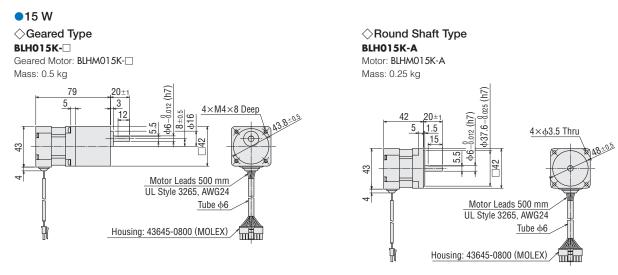
AC Input BX∏

DC Input BLH

AC Speed Control Motors

Dimensions Unit: mm

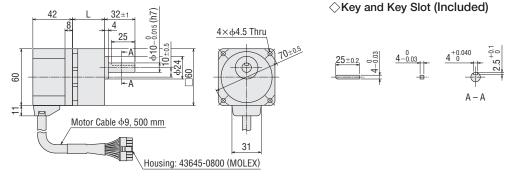
Mounting screws are included with the combination type. Dimensions for mounting screws → Page D-162
 A number indicating the gear ratio is entered where the box □ is located within the product name.



•30 W

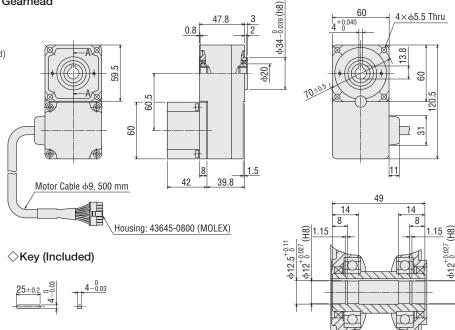
◇Motor/Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	34	
BLH230KC-	BLHM230KC-GFS	GFS2G□	30~100	38	1.0
			200	43	1



◇Motor/Hollow Shaft Flat Gearhead BLH230KC-□FR

Motor: BLHM230KC-GFS Gearhead: GFS2G_FR Mass: 1.3 kg (including gearhead)

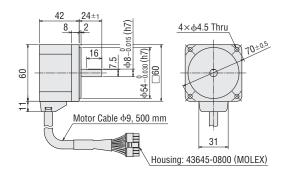


Page Features D-90 / System Configuration D-91 / Product Line D-92 / Specifications D-92 / Characteristics D-93 Dimensions D-96 / Connection and Operation D-100 / Motor and Driver Combinations D-103

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A – A

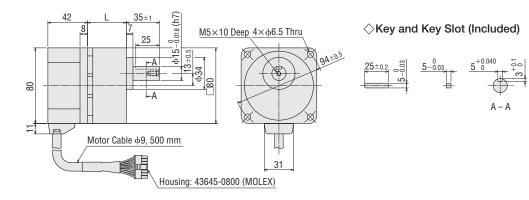
◇Round Shaft Type BLH230KC-A Motor: BLHM230KC-A Mass: 0.5 kg



•50 W

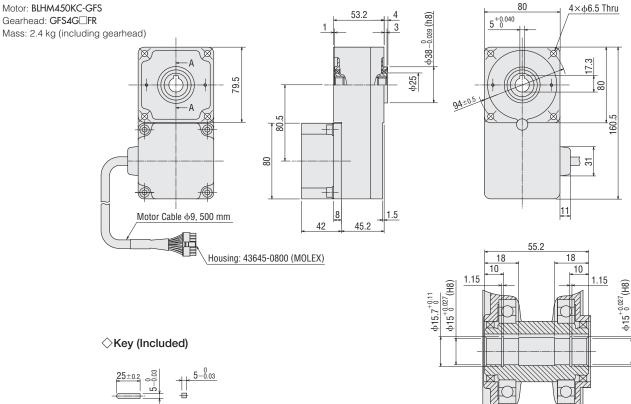
◇Motor/Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass kg
			5~20	41	
BLH450KC-	BLHM450KC-GFS	GFS4G□	30~100	46	1.8
			200	51]



◇Motor/Hollow Shaft Flat Gearhead BLH450KC-□FR

Motor: BLHM450KC-GFS Gearhead: GFS4G FR



 $\mathsf{A} - \mathsf{A}$

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Overview, Product

Brushless Motors

AC Input BMU

AC Input BLE2

AC Input BXII

DC Input BLH

AC Speed

Control

Motors

DSC

US2

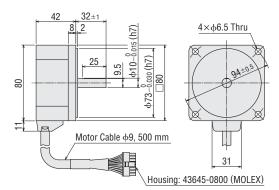
Accessories

Installation

Series

◇Round Shaft Type BLH450KC-A

Motor: BLHM450KC-A Mass: 0.8 kg

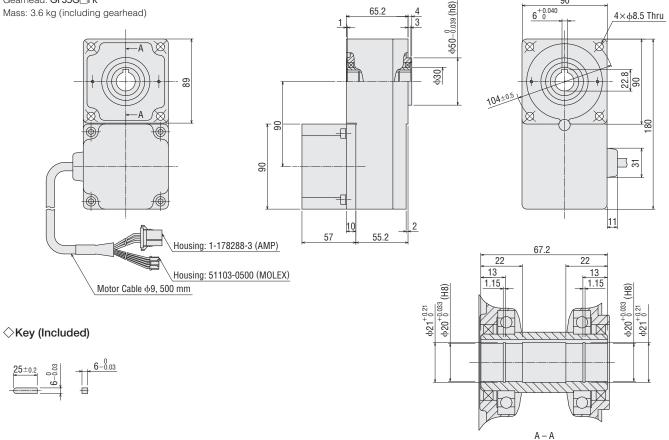


•100 W

◇Motor/Parallel Shaft Gearhead Product Name Motor Product Name Gearhead Product Name Gear Ratio L Mass kg 5~20 45 BLH5100KC-BLHM5100KC-GFS 30~100 GFS5G 58 2.9 200 64 57 42±1 -0.018 (h7) 10 5 34 ± 0.5 M6×12 Deep 4×48.5 Thru 25 0.5 φ18-104±0.5 \mathcal{A} -A 6 =1 Motor Cable ϕ 9, 500 mm IJ Housing: 1-178288-3 (AMP) 31 Housing: 51103-0500 (MOLEX)

OMotor/Hollow Shaft Flat Gearhead BLH5100KC-□FR

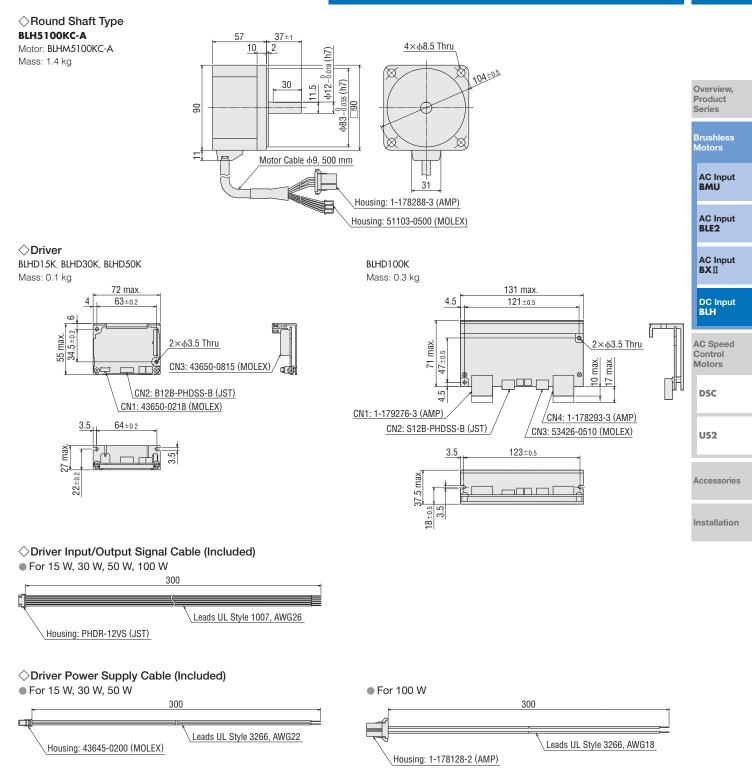
Motor: BLHM5100KC-GFS Gearhead: GFS5G FR



Page Features D-90 / System Configuration D-91 / Product Line D-92 / Specifications D-92 / Characteristics D-93 Dimensions D-96 / Connection and Operation D-100 / Motor and Driver Combinations D-103

90

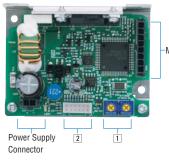
Brushless Motors/AC Speed Control Motors D-99



Connection and Operation

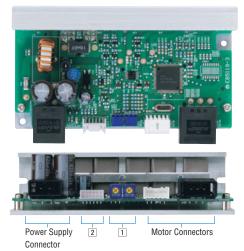
Names and Functions of Driver Parts

◇15 W/30 W/50 W



-Motor Connector

◇100 W



2 I/O Signals

Indication	I/0	Pin No.	Function
	Output	1	ALARM Output
	Output	2	SPEED Output
	I/O Signal Common	3	GND
		4	VRL Input
	Analog Input	5	VRM Input
CN2		6	VRH Input
GNZ	Input	7	ALARM-RESET Input
		8	INT. VR/EXT Input
		9	CW/CCW Input
		10	RUN/BRAKE Input
		11	START/STOP Input
		12	NC

◇100 W

Driver Power Supply Connection Red +24 V* 2 Connect to 24 VDC (±10%) Black CN1 GND* power supply 1 *The connection position is different from the position for the 15 W, 30 W and 50 W models. 12 NC Black Start/Stop Input (ON: Start) 11 START/STOP Brake Input (OFF: Instantaneous Stop) White Brake Input (OFF: Instantaneous Stop) White Rotation Direction (OFF: CCW) Gray Switching Input (OFF: CCW) Gray Speed Potentiometer (ON: Internal Selection Input (OFF: External) Light Blue RUN/BRAKE 10 9 CW/CCW 8 INT. VR/EXT Input Alarm Reset Input OFF: Normal Operation 7 ALARM-RESET Input CN2 (I/O)6 VRH Green 5 VRM Speed Setting 0~5 VDC (+ DC Power Supply Yellow 1 mA min. 4 VRL Orange 3 GND GND Red Speed Output 2 SPEED Output Brown Alarm Output ALARM Output 1 Acceleration/Deceleration Time Potentiometer 4 Ð Internal Speed Potentiometer Motor CN3 Motor Motor CN4

1 Speed Potentiometer

Indication	Potentiometer Name	Function
VR1	Internal Speed Potentiometer	Set and adjust the operating speed of the motor.
VR2	Acceleration/Deceleration Time Potentiometer	Set a common acceleration/deceleration time in the range of $0.5{\sim}10$ seconds.

Connection Diagrams

\diamondsuit 15 W/30 W/50 W

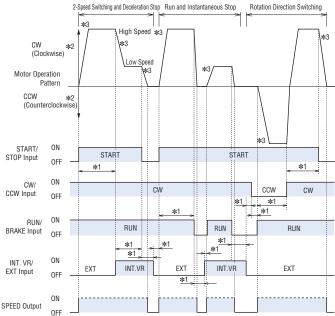
		D		D	river	
	Supply Connection t to 24 VDC (±10%)	Black	2	GND		
powers	· · · · ·	Red	1	+24 V		CN1
			12	NC		
Start/S	top Input (ON: Start)	Black	11	START/STO)P	
Brake Input	ON: Run OFF: Instantaneous Stop	White	10	RUN/BRAK	E	
Rotation Di Switchin	g Input (ON: CW)	Gray	9	CW/CCW		
Speed Pote Select	ntiometer (ON: Internal tion Input (OFF: External)-	Light Blue	8	INT. VR/EX	T Input	
	et Input (ON: Reset OFF: Normal Operat	Purple	7	ALARM-RE	SET Input	CN2
			6	VRH		(1/0)
Speed Setting	0~5 VDC +	Green	5	VRM		
DC Power Supply	1 mA min.	Yellow	4	VRL		
GND	_	Orange	3	GND		
Speed Output		Red	2	SPEED Out	put	
Alarm Outpu	t	Brown	1	ALARM Ou	tput	
Acceler Ti	ation/Deceleration me Potentiometer		Þ		·	
Internal Sp	eed Potentiometer ——		Ð		CN3	
					Moto	r 🛛
					1	
					Motor	

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Brushless Motors/AC Speed Control Motors D-101

Timing Chart



*1 At least 10 ms

*2 The direction applies to the motor alone. The specific direction will vary depending on the gear ratio.
*3 The motor will start/stop over the time set by the acceleration/deceleration time potentiometer.

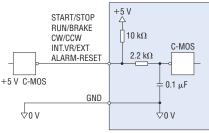
Input/Output Signal Circuits

◇Input Circuit

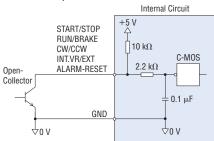
The driver's signal inputs use the C-MOS input method.

- The signal status indicates a voltage level of 0 to 0.5 V when the signal is ON, or 4 to 5 V when it is OFF.
- 5 V C-MOS Output from External Control Device

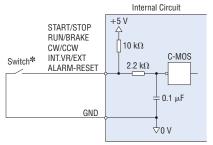




Open-Collector Output from External Control Device



Switch Connection



*Use a switch capable of opening/closing the current flow at 5 VDC, 1 mA maximum.

- All operations of run/stop, instantaneous stop and rotation direction switching operations can be controlled with the START/STOP, RUN/BRAKE and CW/CCW signals.
- If both the START/STOP signal and the RUN/BRAKE signal are set to ON, the motor rotates. The motor will accelerate over the time set by the acceleration/deceleration time potentiometer. During this time, if the CW/CCW signal is set to ON, the motor rotates clockwise as viewed from the shaft end of the motor; if the CW/CCW signal is set to OFF, the motor rotates in the counterclockwise direction.
- If the RUN/BRAKE signal is set to OFF while the START/ STOP signal is ON, the motor stops instantaneously. If the START/STOP signal is set to OFF while the RUN/BRAKE signal is ON, the motor will stop with deceleration time set by the acceleration/deceleration time potentiometer.
- The duration of each input signal must be 10 ms or longer.
- Do not operate (turn ON/OFF) two or more input signals simultaneously. There must be a minimum interval of 10 ms before another input signal can be operated after an input signal has been operated.

Brushles: Motors

AC Input BMU AC Input BLE2 AC Input BXII DC Input BLH

AC Speed Control Motors

DSC

US2

Accessories

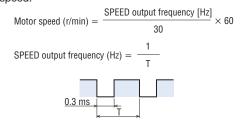
Installation

Output Circuit +26.4 VDC max 10 mA max Internal Circuit SPFFD \downarrow R ALARM 2SC2458 or Insert a resistor to Fauivalent keep the current to 10 mA or less. GND ↓₀v Υoγ

♦ SPEED Output

The system outputs pulse signals (with a width of 0.3 ms) at a rate of 30 pulses per rotation of the motor output shaft synchronized with the motor operation.

You can measure the SPEED output frequency and calculate the motor speed.



◇ALARM Output

The ALARM output is normally ON and goes OFF when there is an alarm.

◇ALARM-RESET

When the motor is stopped, setting this signal ON, then returning it to OFF resets the alarm.

Please return either the START/STOP input or the RUN/BRAKE input to OFF before inputting the ALARM-RESET. The ALARM-RESET is not accepted if both these signals are ON.

Note

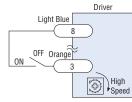
Output signal is open-collector output, so an external power supply (Vcc) is required.
 Use a power supply of no more than 26.4 VDC and connect a limit resistor (R) so that the output current does not exceed 10 mA. When using neither the speed output function nor the alarm output function, this connection is not required.

Speed Setting Method

◇Internal Speed Potentiometer

When INT.VR/EXT input is set to ON, the speed can be set with the internal speed potentiometer.

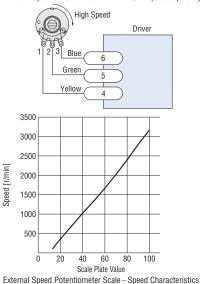
There is no need for this connection when the internal speed potentiometer is not used.



External Speed Potentiometer (Sold separately)

When separating the motor speed setting from the driver, connect the accessory external speed potentiometer as follows.

External Speed Potentiometer **PAVR-20KZ** (Sold separately)

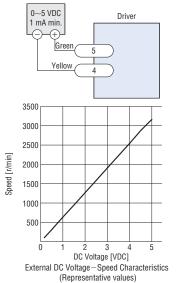


(Representative values)

◇External DC Voltage

When setting the motor speed with an external DC voltage, do so in the following manner.

External DC Power Supply



Note

• The speed in the graph represents the speed of a motor alone. The gearhead output shaft speed of the combination type or geared type is calculated by dividing the graph speed by the gear ratio.

Multi-Motor Control

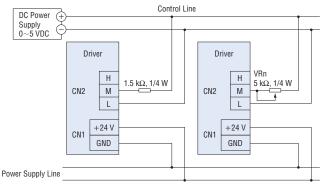
Two or more sets of motor and driver can be operated at the same speed by using a DC power supply or an external speed potentiometer.

\bigcirc When External DC Power Supply is Used

• Use a DC power supply with current capacity equal to or greater than the value obtained by the following expression.

Current capacity (N is the number of drivers) $I = 1 \times N$ (mA) Example: When two drivers are used, current capacity should be at least 2 mA.

- Connect the other input/output lines to each driver individually.
- Motor speed differences can be adjusted by connecting a resistor of 1.5 kΩ, 1/4 W to the M terminal of the first driver, and a 5 kΩ, 1/4 W variable resistor (VRn) to the M terminals of the other drivers.



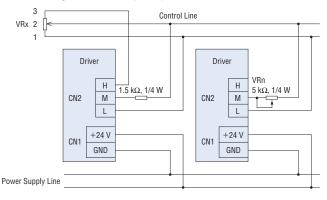
\bigcirc When External Speed Potentiometer is Used

As shown below, make the power supply line and the speed control line common to set the speed at VRx.

 The required resistance of the external speed potentiometer is calculated by the following expression.

Resistance value (N is the number of drivers) VRx = 20/N (k Ω), N/4 (W) Example: When two drivers are used, the resistance is 10 k Ω , 1/2 W.

- Connect the other input/output lines to each driver individually.
- Motor speed differences can be adjusted by connecting a resistor of 1.5 k Ω , 1/4 W to the M terminal of the first driver, and a 5 k Ω , 1/4 W variable resistor (VRn) to the M terminals of the other drivers.
- No more than five motors should be operated simultaneously when using the external speed potentiometer.



List of Motor and Driver Combinations

Geared Type

The geared type has an integrated motor and gearhead. The combination of motor and gearhead cannot be changed.

Output Power	Product Name	Geared Motor Product Name	Driver Product Name
15 W	BLH015K-	BLHM015K-	BLHD15K

Combination Type – Parallel Shaft Gearhead

The combination type comes with the motor and parallel shaft gearhead pre-assembled.

Output Power	Product Name	Motor Product Name	Gearhead Product Name	Driver Product Name
30 W	BLH230KC-	BLHM230KC-GFS	GFS2G	BLHD30K
50 W	BLH450KC-	BLHM450KC-GFS	GFS4G	BLHD50K
100 W	BLH5100KC-	BLHM5100KC-GFS	GFS5G	BLHD100K

Combination Type – Hollow Shaft Flat Gearhead

The combination type comes with the motor and hollow shaft flat gearhead pre-assembled.

Output Power	Product Name	Motor Product Name	Gearhead Product Name	Driver Product Name
30 W	BLH230KC-□FR	BLHM230KC-GFS	GFS2G□FR	BLHD30K
50 W	BLH450KC-□FR	BLHM450KC-GFS	GFS4G□FR	BLHD50K
100 W	BLH5100KC-	BLHM5100KC-GFS	GFS5G□FR	BLHD100K

Round Shaft Type

Output Power	Product Name	Motor Product Name	Driver Product Name
15 W	BLH015K-A	BLHM015K-A	BLHD15K
30 W	BLH230KC-A	BLHM230KC-A	BLHD30K
50 W	BLH450KC-A	BLHM450KC-A	BLHD50K
100 W	BLH5100KC-A	BLHM5100KC-A	BLHD100K

AC Input BXII

Overview, Product Series

Brushless Motors

> AC Input BMU

AC Input BLE2

DC Input BLH

AC Speed Control Motors

DSC

US2

Accessories

Installation

lacksquare A number indicating the gear ratio is entered where the box \Box is located within the product name.